

Units of Measure for Hybrid Programs

15-424 Final Project

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Hybrid systems, differential dynamic logic, and KeYmaera X

$$[\alpha]P$$

- This is a **hybrid program**, which models a **hybrid system**
- It is a **formula** in $d\mathcal{L}$
- **KeYmaera X** is a theorem prover for $d\mathcal{L}$

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Verifying a model vs validating it

- **Verification** can be done in the proof calculus of $d\mathcal{L}$ (and can be partially automated/fully checked by KeYmaera X)
- **Validation** is checking if a model is actually representative of the system it's supposed to be modelling
- A difficult problem, *but* there are some things we can do purely syntactically—including this!

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Example 1: The weirdly-accelerating car

- Consider the hybrid program on the right, meant to model a 1D car that has to stop before some point
- ODE, instead of $x' = v$, has $x' = x$ (which doesn't make sense physically)
- Serious mistake; model is not a car moving in a straight line
- But it passes muster in KeYmaera X 4.2b1!
- User might waste plenty of time trying to verify an unprovable model

```
ProgramVariables.  
  R x.  
  R S.  
End.  
Problem.  
  [{  $x' = x$  }] x <= S  
End.
```

Figure: An incorrect model of a 1D car

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Example 2: The neat new distance metric

- Lab 3 of 15-424 involved modelling a robot travelling around a circular track and verifying that it would stop before it ran into an obstacle
- A student submitted a model hinging on the test given below:
- Subtracts a quantity with dimension L from a quantity with dimension L^2
- Subtle problem—mostly a safe if unnecessarily conservative overapproximation, *except* if $ox - x < 1$? What happens then?

$$\begin{aligned} &?((ox-x)^2 + (oy-y)^2 - v*T - (a*T^2))/2 \\ &\geq -((v + a*T)^2)/(2*B); \end{aligned}$$

Figure: An incorrect test

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Figure: An incorrect test

How do we fix this?

- Units of measure!
- Physics people realise that comparing incommensurate quantities doesn't make sense
- CPS verification is “physics stuff”!

The weirdly-accelerating car revisited

We can annotate the incorrect model of the 1D car with units, and see what happens!

```
ProgramUnits.  
  U m.  
End.  
ProgramVariables.  
  R x : m.  
  R S : m.  
End.  
Problem.  
  [{ x' = x }]x <= S  
End.
```

Figure: The incorrect model of the 1D car with unit annotations

The weirdly-accelerating car revisited

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ProgramUnits.  
  U m.  
End.  
ProgramVariables.  
  R x : m.  
  R S : m.  
End.  
Problem.  
  [{ x' = x }]x <= S  
End.
```

Figure: The incorrect model of the 1D car with unit annotations

Unit analysis error

Units do not match in expression $x' = x$

$$\begin{array}{ccc} x' & = & x \\ \wedge \text{ m*s}^{-1} & & \wedge \text{ m} \end{array}$$

The neat new distance metric revisited

We isolate the problematic test in an annotated hybrid program, and see what happens.

```
ProgramUnits.          Problem.
  U m.                [?( (ox-x)^2 + (oy-y)^2 - v*T
End.                  - (a*T^2)/2
ProgramVariables.     >= -((v + a*T)^2)/(2*B));] x=x
  R ox : m.          End.
  R x : m.
  R oy : m.
  R y : m.
  R a : m/(s*s).
  R T : s.
  R v : m/s.
  R A : m/(s*s).
  R B : m/(s*s).
End.
```

The neat new distance metric revisited

```
ProgramUnits.          Problem.
  U m.                 [?((ox-x)^2 + (oy-y)^2 - v*T
End.                   - (a*T^2)/2
ProgramVariables.     >= -((v + a*T)^2)/(2*B)];]x=x
  R ox : m.           End.
  R x : m.
  R oy : m.
  R y : m.
  R a : m/(s*s).
  R T : s.
  R v : m/s.
  R A : m/(s*s).
  R B : m/(s*s).
End.
```

Unit analysis error

unit error in term on LHS of >=

Problematic term is $(ox-x)^2+(oy-y)^2-v*T-a*T^2/2$

Units for $d\mathcal{L}$ and KeYmaera X

- We developed a monomorphic unit-of-measure type system with a top type for $d\mathcal{L}$
- We built a working implementation in the current version of KeYmaera X
- Our version of KeYmaera X is entirely backward-compatible with the existing version—the presence of \top in the type system means that we can assign any unannotated variables type \top and hence programs written without explicit units still typecheck.

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Unit-checking $d\mathcal{L}$

Some rules for checking terms

$$\text{Times-T} \frac{\Upsilon \vdash x_1 : \tau_1 \quad \Upsilon \vdash x_2 : \tau_2}{\Upsilon \vdash x_1 \times x_2 : \tau_1 \cdot \tau_2}$$

$$\text{Div-T} \frac{\Upsilon \vdash x_1 : \tau_1 \quad \Upsilon \vdash x_2 : \tau_2}{\Upsilon \vdash x_1 \div x_2 : \tau_1 \cdot \tau_2^{-1}}$$

Figure: Representative examples of rules for typing $d\mathcal{L}$ terms

Unit-checking $d\mathcal{L}$

Example (times)

$$\text{Times-T} \frac{\text{Var-T} \frac{\Upsilon(x) = m}{\Upsilon \vdash x : m} \quad \text{Var-T} \frac{\Upsilon(y) = m}{\Upsilon \vdash y : m}}{\Upsilon \vdash x \cdot y : m^2}$$

Unit-checking $d\mathcal{L}$

Example (divide)

$$\text{Times-T} \frac{\text{Var-T} \frac{\Upsilon(x) = m}{\Upsilon \vdash x : m} \quad \text{Var-T} \frac{\Upsilon(t) = s}{\Upsilon \vdash t : s}}{\Upsilon \vdash x/y : m \cdot s^{-1}}$$

Checking $d\mathcal{L}$ formulas

Rule

$$\text{=-ok} \frac{\Upsilon \vdash t_1 : \tau \quad \Upsilon \vdash t_2 : \tau}{\Upsilon \vdash t_1 = t_2 \text{ ok}}$$

Figure: Representative example of rules for validating $d\mathcal{L}$ formulas

Checking $d\mathcal{L}$ formulas

Example

$$=ok \frac{\begin{array}{c} \vdots \\ \Upsilon \vdash x : m \end{array} \quad \begin{array}{c} \vdots \\ \Upsilon \vdash y : m \end{array}}{\Upsilon \vdash x = y \quad ok}$$

Checking d \mathcal{L} programs

$$\text{;-runs} \frac{\Upsilon \vdash P_1 \text{ runs} \quad \Upsilon \vdash P_2 \text{ runs}}{\Upsilon \vdash P_1; P_2 \text{ runs}}$$

$$\text{ODE-runs} \frac{\Upsilon \vdash x : \tau \quad \Upsilon \vdash t : \tau \cdot s^{-1}}{\Upsilon \vdash \{ x' = t \} \text{ runs}}$$

Figure: Representative examples of rules for validating d \mathcal{L} programs

Adding units to KeYmaera X

- We implemented unit of measure types and a unit-checker in KeYmaera X in accordance with the rules given on previous slides.
- Only very minor modifications to the KeYmaera X core (the soundness-critical part of KeYmaera X)!
- Only addition of a new datatype to expressions to support units
- If you trusted KeYmaera X previously, you can still trust it now!

The normally-accelerating car

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End.  
ProgramVariables.  
  R x : m.  
  R v : m/s.  
  R S : m.  
End.  
Problem.  
  [{ x' = v }]x <= S  
End.
```

Figure: A corrected model of the 1D car. Will pass the unit checker!

Future work

- Fruitful avenue of validating hybrid systems models without having to build the real system
- Units of measure lend themselves to other interesting applications within KeYmaera X
 - ▶ Constraining invariant/proof search?
 - ▶ Improved user interface?

Conclusion

- Unit analysis is easy
- ... for computers!
- Fully automatable, and fully automated!
- Find more bugs today!

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Questions?