

**Assignment 1: Introduction to Hybrid Programs**  
**15-424/15-624 Foundations of Cyber-Physical Systems**  
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Total Points: 60

**1. Term, formula, hybrid program, or none of the above?**

For each of the following, determine if the expression is a  $\mathbf{dL}$  term, a well-formed  $\mathbf{dL}$  formula, a well-formed hybrid program, or none of the above (ie. it is not well-formed). In the case that the expression is none of the above, give a short explanation.

- (a)  $?(3 > 2)$
- (b)  $[x := 1; \{x'' = x\}](-1 \leq x \wedge x \leq 1) \leftrightarrow [y := \cos z](-1 \leq y \wedge y \leq 1)$
- (c)  $x = 42$
- (d)  $x := y \cup x := z$
- (e)  $(x > y)^*$
- (f) 42
- (g)  $L > 0 \wedge U > 0 \rightarrow [(x := *; ?(L < x \wedge x < U))^*](x = y)$
- (h)  $x$
- (i)  $y := \pi$
- (j)  $(x > y \wedge (y > z \cup y > w))$
- (k)  $x := 0 \rightarrow [\{x' = 1, y' = 1 \ \& \ y \leq 10\}]x \leq 10$
- (l)  $(x := x + 1)^*$
- (m)  $\forall x \exists y (x < y)$
- (n)  $[x := 42]$
- (o)  $x := y^2$
- (p)  $y > 1 \wedge z > 1 \rightarrow [x := z^y](x > z)$
- (q)  $[x = y; y = z]?(x \geq z)$

**2. Practice writing hybrid programs.**

- (a) The if-then-else construct is not actually in the grammar of hybrid programs; it's just syntactic sugar. Write an equivalent hybrid program which does not depend on if-then-else:

$\text{if } (x^2 \geq 5 \wedge x \leq 0) \ x := x - 1 \ \text{else } x := x + 1$

- (b) Non-deterministic Choice: Write a hybrid program that assigns either  $a$  or  $b$  to the variable  $x$ .

### 3. Safety and Contracts

- (a) A *safety* property is something that a cyber-physical system should *always* maintain. Describe a cyber-physical system and then name three safety properties that it should never violate.
- (b) Suppose you want to prove that a property  $\phi$  is a safety property of hybrid program  $\alpha$ , i.e. that  $\phi$  holds under all possible runs of hybrid program  $\alpha$ . Write the  $\mathbf{dL}$  formula that expresses this.
- (c) Now, suppose you want to prove that, given initial conditions  $\psi$ , another property  $\phi$  is a safety property of hybrid program  $\alpha$ . Write the  $\mathbf{dL}$  formula that expresses this.
- (d) Consider hybrid program  $\alpha$ :

$$\alpha \equiv x := w; ((y := 3; z := 20) \cup (z := 6; y := w + 7)); \{x' = 10\}; ?(y \leq 30)$$

For each variable in  $\alpha$ , list the set of all values they can reach at the end of a run of  $\alpha$ .

- (e) Come up with at least two properties that hold at the end of all runs of  $\alpha$  (example:  $y \leq 30$  is a property that the program always satisfies, but now you can't use upper bounds on  $y$ ). Write down a  $\mathbf{dL}$  formula which is true iff hybrid program  $\alpha$  always satisfies those properties.

### 4. Non-Deterministic Evolution

$$\beta \equiv x := x_0; v := v_0; t := 0; \{x' = v, v' = a, t' = 1 \ \& \ v \geq 0\}; ?(v = 0)$$

- (a) Assume that  $a < 0 \wedge v_0 \geq 0$ . At the end of a run of hybrid program  $\beta$ , what is the value of  $t$  as a function of  $x_0$ ,  $v_0$ , and  $a$ ?
- (b) Suppose we remove the guard  $?(v = 0)$  at the end of hybrid program  $\beta$ . Again assuming that  $a < 0 \wedge v_0 \geq 0$ , what are the possible values of  $t$  at the end of any run of this modified version of  $\beta$ ?
- (c) Suppose we assume instead that  $a < 0 \wedge v_0 \leq 0$  ( $v_0$  is **less than** or equal to zero). What are the possible values of  $t$  at the end of any run of  $\beta$ ?